## Bus Arrival Time Prediction with LSTM Neural Network

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## Task definition

- Public transport arrival time prediction to stops
- Take into account different factors that characterize the traffic state
- Develop a distributed prediction model


## Task

- Real-time processing
- High accuracy


## Initial data. Preprocessing

- GPS coordinates are obtained every 30 seconds
- Coordinates are fitted using information about the road network geometry and transport routes
- Travel times for each road link are calculated



## Problem formulation

- $S$ is the set of stops;
- $R$ is the set of routes;
- $N$ is the maximum number of route links;
- $t_{i}^{d e p}$ the departure time from stop $i \in S$;
- $t_{j}^{\text {arr }}$ is the arrival time at stop $j \in S$;
- $T_{i j}^{\text {travel }}$ the travel time between stops $i$ and $j$.

$$
t_{j}^{a r r}=t_{i}^{d e p}+T_{i j}^{\text {travel }}
$$

## Feature vector: base factors

To estimate the travel time $T_{i j}^{\text {travel }}$ we used the following factors:

- day, time
- $v_{i-1, i}$ - travel speed on the previous route link
- $h^{r}$ - time headway to the preceding vehicle with the same route
- $T_{i j}^{m, r}$ travel time of the preceding vehicle $m$ with the same route $r$
- $\tilde{T}_{i j}^{r}$ - weighted travel time of preceding vehicles with the same route:

$$
\tilde{T}_{i j}^{r}=\frac{\sum_{k \in N_{r}} \omega\left(t-t_{i}^{\text {dep }, k}\right) T_{i j}^{\text {travel }, k}}{\sum_{k \in N_{r}} \omega\left(t-t_{i}^{\text {dep }, k}\right)}
$$

## Feature vector

- $h^{\text {any }}$ - time headway to the preceding vehicle with any route
- $T_{i j}^{m, a n y}$ - travel time of the preceding vehicle with any route
- $\tilde{T}_{i j}^{\text {any }}$ - weighted travel time of preceding vehicles with any route
- $T_{i j}^{\text {hist }}(t)$ - historical average travel time
- $T_{i j}^{\text {fow }}(t)$ - historical average travel time by traffic flow data
- $c_{i j}$ - number of vehicles on the targeted route link

$$
X_{i, j}=\left(\text { day }, \text { time }, v_{i-1, i}, h^{r}, T_{i j}^{m, r}, \tilde{T}_{i j}^{r}, h^{a n y}, T_{i j}^{m, a n y}, \tilde{T}_{i j}^{a n y}, T_{i j}^{h i s t}, T^{f o w}, c_{i j}\right)
$$

## Long short-term memory (LSTM) cell

$h_{\mathrm{t}}{ }^{\hat{4}}$


## LSTM network



## Long short-term memory (LSTM) neural network

Input data


Output data


## Model analysis

## Comparison:

- Proposed / Base LSTM models
- ANN, 1 hidden layer
- Linear Regression

$$
\mathrm{MAE}=\frac{1}{n} \sum_{t=1}^{n}\left|V_{t}-\hat{V}_{t}\right|
$$

$$
\mathrm{MAPE}=\frac{1}{n} \sum_{t=1}^{n} \frac{\left|V_{t}-\hat{V}_{t}\right|}{V_{t}} \times 100 \%
$$



## Data set:

- Five bus routes
- Average route length is 16 km
- Travel time observations in 30 days


## Model analysis. MAE / MAPE

Table: Algorithms Comparison

|  | MAE | MAPE |
| :--- | :---: | :---: |
| LSTM | $\mathbf{2 2 . 1 2}$ | $\mathbf{1 9 . 7 8}$ |
| Base LSTM | 23.64 | 21.24 |
| ANN | 25.54 | 23.25 |
| Regression | 26.89 | 25.19 |



## Model analysis. MAE / MAPE for routes




## Model analysis. MAE / MAPE

MAE, seconds


MAPE, \%


## Model analysis. Execution time

Intel Core i5-3740 3.20 GHz, 8 GB RAM / Nvidia GeForce GTX 1080 Ti



## Conclusion

The proposed LSTM based arrival time prediction model has the following advantages:

- Combines different factors describing the traffic situation.
- It has high prediction accuracy.
- It has a low computation time.


# Thank you! 

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